

Classification of SAR Images

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Abstract: Our basic objective is to classify the given SAR (Synthetic Aperture Radar) images into water, ice, vegetation, and urban areas and remove any kind of noises in the sea-ice classification. Land spread characterization of SAR Images requires use of spatial relationship of pixels likewise, pixel level segmentation. SAR picture can be segmented effectively if the regions with homogeneous intensity and texture ranges can be distinguished and assembled together. A supervised classification algorithm has been used to classify the SAR images. The given monotone and textured regions are labeled as water and urban areas using SVM classification. Any kind of speckle noise is also removed. We extract the features and decrease inaccuracies of noise on details. The order and precision of the classification has also improved by going through the above process. Upon comparing the output image obtained with the topographical map of the region, we found out that the classification approach used is similar.

Index Terms—SAR-Synthetic Aperture Radar, SVM-Support Vector Machine, GLCM-Gray level Co-occurrence matrix

1. Introduction

Land spread mapping utilizing SAR pictures is a critical region of examination. Since SAR sensors give unsurpassed and all-weather looking over, probability of utilizing SAR pictures as a part of different applications like area spread grouping, object location is to be investigated. Order of area spread into classes like water, urban and vegetation helps in arranging and administration of urban districts, for example, practical advancement and brilliant development. Division is an essential procedure of computerized picture handling with an extreme objective of enhancing a picture for ensuing investigation and scene portrayal. A picture can be portioned into classes in light of dark levels, surfaces, edges and so on. A single band and single polarized SAR picture contain data just as power and surface. Division of single band, single polarized SAR picture is drawn closer by two established procedures: Supervised and Unsupervised. Supervised classification of SAR Images requires preparing tests and from the earlier data about the

locale like computerized rise map and so forth. Unsupervised arrangement of SAR pictures requires no from the earlier data about the picture. For segmentation and marking of classes, the algorithm extracts data from the picture itself. In this paper, we show a calculation for unsupervised characterization of SAR pictures by block based segmentation and contour tracing. We section the SAR picture into monotone, texture zones and edges. The monotone and textural areas are moreover differentiated according to the intensity and textural patterns. MRFs (Markov Random Field) have been used to model image textural features. But the main drawback of MRF algorithms is that the fine structures like 1-3 pixel wide line segments may disappear partially or entirely and region borders are not precisely located. Statistical Image model may not be accurate enough and classes are overlapped in the feature space. This results in some confusion in data classification inhomogeneous areas as well as at region borders or close to fine structures. In this paper, we approach SAR picture division issue as piece based division. SAR picture is separated into pieces. At that point, every piece is broke down for its homogeneity of dark levels, textural examples and edges. Pieces are assembled and marked by attributes. Edge pieces are checked for its progression and shape is followed. Edge availability helps in expulsion of commotion and enhances grouping exactness. Area naming is done to associate nearby homogenous squares. In this procedure, any detached homogenous or edge obstructs with little locales are marked as undecided. These undecided pieces are relegated to the neighboring homogenous areas in the last stride. SVM grouping is performed on the square based portioned picture and water, urban and vegetation territories are recognized. Ocean ice is a composite which is comprised of immaculate ice crystal, brine, bubble and different impurities. Its freezing, melting what's more, floating have awesome impact on ocean jobs, what's more, it may even make hurt life and property.

2. Literature Survey

The possibility of Synthetic Aperture Radar (SAR) Images for area spread mapping is a critical region of examination [1]. For Single band, single captured SAR Image, data is accessible as Intensity and

surface as it were. Land spread order of SAR Images requires misuse of spatial relationship of pixels likewise, notwithstanding pixel level division. SAR picture can be divided effectively if the locales with homogeneous force and surface regions can be recognized and gathered together. As such, shape following has been utilized just as a part of dividing ocean and area.

Recognizing shapes in a trained territory with a blend of water, urban and vegetation ranges require complex examination of spatial circulation of pixels. In this paper, we have exhibited an unsupervised characterization calculation utilizing Maximum a posteriori (MAP) division for SAR pictures in which SAR picture is arranged into monotone, surface and edge districts. Monotone and finished locales are marked as area spread sorts like water, urban and vegetation zones utilizing K-implies characterization. SAR Image of the area with scope shifting from 77.86o to 77.91o and longitude changing between 29.89 o and 29.85 o of Haridwar locale, India is considered for division. We have looked at the fragmented picture got by this philosophy with the topographic guide of the comparing locale. The water, urban and vegetation territories are unmistakably perceived with proposed characterization approach which speaks to a decent concurrence with the first topographic sheet.

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In this paper, we approach SAR picture division issue as piece based division. SAR picture is separated into pieces. At that point, every piece is broke down for its homogeneity of dark levels, textural examples and edges. Pieces are assembled and marked by attributes. Edge pieces are checked for its progression and shape is followed. Edge

availability helps in expulsion of commotion and enhances grouping exactness. Area naming is done to associate nearby homogenous squares. In this procedure, any detached homogenous or edge obstructs with little locales are marked as undecided. These undecided pieces are relegated to the neighboring homogenous areas in the last stride. K-implies grouping is performed on the square based portioned picture and water, urban and vegetation territories are recognized.

Grouping Methodology

When monotone and edge squares are distinguished, all the rest of the pieces can be considered as surface squares. For all these surface squares, highlight vectors are extricated to separate different surface examples. Wavelet change is utilized has the piece region of the square isolated by an edge

Area Labeling

Once the picture squares are distinguished as monotone, surface and edge pieces, and the pieces neighboring each other and have the same force and surface are associated and a typical locale mark is given. For every piece, eight neighborhood availability is checked for its nearness with neighboring squares. For interfacing monotone pieces, mean and change shape the element vector and textural squares, textural highlight vector including its db4 wavelet segments is utilized for contrasting the neighboring surface pieces. Just comparative piece sorts are contrasted for nearness and consolidated together with structure the same area. Give the component vector a chance to be spoken to as F_{ij} where i, j are piece lists. The two neighboring pieces (i, j) and $(i+1, j)$ have a place with the same district if the accompanying condition is fulfilled.

$$F - F_{2 < T - (2) ij i+1, j}$$

For each district subsequently associated, name or locale number is given so that every area before the end of this procedure speaks to the particular monotone and surface areas. Edge squares are not considered in this procedure.

K-implies order

All picture pieces present in the whole picture are distinguished either as monotone, surface or edge squares and squares with comparative attributes adjoining each other are consolidated and areas are named. K-implies arrangement is connected on the divided picture to distinguish water, urban, vegetation and other unclassified zones.

The geo-referenced and dot smothered SAR picture is of size 302 x 302. At that point, this picture is isolated into picture pieces of measurement 2 x 2 prompting 151 x 151 squares. At that point, mean force and difference are processed for individual

pieces. The limit for difference with mean power is checked and monotone pieces are distinguished. At that point, utilizing MAP based division, edge squares of names level, vertical and corner to corner edges are recognized. Daubechies wavelet change is connected on the picture and textural components are caught. The wavelets coefficients are contrasted with distinguish distinctive surface examples. All the picture squares are in this way marked as one of monotone, surface and edge pieces where each monotone and surface example is named. Area naming is performed to interface adjoining obstructs with comparable force and surface examples. Eight neighborhood availability is utilized for checking the nearness. Every single neighboring locale with comparative force and surface properties are blended and consequently give an unsupervised divided picture with three sorts of districts, specifically monotone, surface and edge areas. Presently, K-implies order is utilized to arrange the divided picture into water, urban and vegetation territories. For registering arrangement exactness, ground truth focuses speaking to water, urban and vegetation territories are taken for reference from topographic sheet

[2] Utilizing JPL AirSAR pictures a system has been created to group every pixel as both of 4 classes: city, level (water, asphalt), short vegetation, or tall vegetation. The method utilizes the backscattered powers as a part of the CO-and cross-polarized channels at L-and C-groups and additionally the stage contrast between the co-polarized channels

The improvement of a proficient calculation allowing automated grouping of calibrated, 16-look, polarimetric SAR pictures utilizing L and C band information. The classification displayed here partitions the picture into four unmistakable classes: Flat, Short Vegetation, Tall Vegetation, and City. This is finished with an extremely basic characterization procedure taking into account thresholds of some fundamental picture measures. The classifier is free of incidence point also.

The goal is that this classified image can then be utilized for some things: following changes in area use after some time, applying soil moisture calculations to appropriate areas, and applying further order classification algorithms inside one or more of the four classes. This classifier just works if there are leaves on the trees, thus mind must be taken to apply it just when fitting.

The strategy utilized as a part of this paper can be broken into two primary assignments:

(1) generation of the correct information

(2) generation of the classification algorithm from the given information.

A few regions of each of the four sorts were depicted in a SAR picture, and histograms of different amounts were extracted for each. The overlap, or lack, was noted for each of the variables and for each of the regions. Thresholds were resolved on gatherings of variables that would isolate one class from the rest, each one in turn, until every one of the four were isolated and the picture was characterized. The variables used at both L and C bands were as follows: U(hh, vv and hv), Texture (hh, vv and hv), Aco and Cco.

Algorithm used:

1. Begin with an aligned 1G-look picture with both Land C groups.
2. Generate the 16 separate images. L band (PWRLhh) L-Band(PWRLVV), L band (PWRLhv), C band (PWRC hh), C band (PWRCVV), C band (PWRC hv), Texture, hh, L band (TEXLhh), Texture, vv, L band (TEXLVV), Texture, hv, L band (TEXLhv), Texture, hh, C band (TEXChh), Texture, vv, C band (TEXCVV), Texture, hv, C band (TEXChv), hh-vv, L band (AcoL), hh-vv, C band (AcoC), L-band (Ccol), C-Band(CcoC).
3. Apply algorithm to find out city , tall vegetation, short vegetation and flat.

The city pixels all have high surfaces and their stage insights demonstrate detectable twofold skip strength. Tall vegetation is next, city is the brightest. Short vegetation is darker, with less texture, and level surfaces are darkest, since they reflect most in the specular heading and little is backscattered.

The proposed is a novel picture earlier for the non-parametric Bayesian blend model based unsupervised order of SAR pictures. They adjusted the Normalized Gamma Process earlier that constitutes a more broad type of the Dirichlet Process earlier with a specific end goal to encase the commitment of the neighboring pixels into the characterization plan. This yields an picture arrangement earlier implanted in a blend model that permits vast number of bunches and empowers coming to smoothed grouping maps. Taking into account the arrangement results gotten on manufactured and genuine Terra SAR-X pictures, it is demonstrated that the proposed model is able to do precisely ordering the pixels.

It applies a straightforward iterative redesign plan at a solitary keep running without playing out a various leveled bunching technique as utilized as a part of the beforehand proposed strategies. It is additionally shown that the model request estimation exactness of

the proposed strategy beats the routine limited blend models. Exact area spread characterization from high determination Synthetic Aperture Radar (SAR) pictures has turned into a critical angle in remote detecting applications. The principle issue emerges from the trouble in knowing the accurate number of classes ahead of time.

In this manner the programmed estimation of the obscure number of classes is a testing subject in SAR picture arrangement. We propose an unsupervised SAR picture arrangement calculation that models the circulation of the picture intensities utilizing a non-stationary blend model that encases an adaptable picture arrangement earlier with respect to number of classes.

One of the conventional approaches to decide the quantity of classes is to run the calculations, similar to Expectation-Maximization (EM), a few times for various model requests and fall back on a paradigm, as Bayesian Information Criterion (BIC).

Then again, Bayesian way to deal with picture characterization became appealing in light of the fact that it permits nonparametric estimation of model request. Instead of running a settled request blend display a few times and looking the best arrangement among a few ones, non-parametric Bayesian methodologies permit finding the arrangement by a solitary keep running with the assistance of an adaptable earlier.

It is additionally realized that an order guide can be enhanced by including the spatial data into the characterization model.

We are combining spatial domain and frequency domain texture by using the concept of wavelet transformation and gray level co-occurrence matrix in order to reduce any kind of noise [4]. They have successfully extracted wavelet feature and all the inaccuracies have been overcome which the gray level co-occurrence matrix could not.

The Gray level Co-occurrence matrix takes 2-point distance of image which reflects the spatial relation of relative position different pixels. This classification technique of GLCM is applied for classifying Synthetic Aperture Radar Images.

Critical examination of parameter value, direction, gray level and displacement is done for ice detection statistics. Other fellow researchers have used features of GLCM to distinguish between sea and ice (Standard deviation and inverse difference technique). Similarly other researchers have taken the GLCM parameters on the texture characteristics of SAR images for detection on sea ice. They used BP neural network classification method. The texture and noise characteristics of GLCM in the domain cannot be distinguished and appeared to be inaccurate. Wavelet transformation was used as it has good localization features in time and frequency

domain to suppress the effect of speckle noise in the image classified.

The three transport image radar (space borne imaging radar-C, SIR-C) mutually created by the United States Space Organization and the Italian Space Agency, including China, researchers from 13 nations to partake in its participation programs.

The Gray level co-occurrence matrix (GLCM) depends on the likelihood insights examination of pixels which fulfill certain state of removal relations and gray level. The GLCM is exceedingly subject to the parameters d and θ . Under the condition that the first pictures is not compressed, the values/size of the GLCM is the square of the quantity of dark levels of info images. Author has taken an image and has done the procedure of calculation of GLCM of a given test picture force matrix. The number of dim level is eight and the component qualities are characterized as a likelihood thickness capacity $P(i, j | d, \theta)$.

Texture information comprise of variables, for example, energy, contrast, entropy and homogeneity have been calculated using the formulas.

The adjoining pixels of the radar echo signal for coherence will deliver some arbitrary varieties of dim, demonstrating solid noise qualities. GLCM gives a joint distribution of gray level pairs of adjacent pixels of an image as a result GLCM produces inaccuracies in extraction.

Wavelet transformation overcomes these problems. The DWT gives different frequency sections of the objective sign frequency information. Wavelet examination is a halfway investigation of the signal, at whenever or spatial space investigation of images. Energy of SAR speckle noise fundamentally focuses on the high frequency. If the SAR pictures is decayed, a large portion of the noise will be deteriorated into the high-frequency band and the impact of spot noise in the low frequency sub-band will be enormously diminished.

The DWT feature of wavelet transformation is used for SAR image. Scaling and translation transformations are used in the wavelet functions.

A substantial unsupervised and multi-scale order technique of manufactured opening radar (SAR) symbolism is proposed based on the Expectation Maximization and the hereditary calculation (GA-EM). This calculation is equipped for selecting the quantity of grouping of SAR picture utilizing the Bayesian data standard (BIC) for Gaussian blend model. As of late, SAR imaging has been quickly picking up in applications, for example, remote detecting, surface observation, and programmed target acknowledgment. For these applications, the order of different classifications of

Disarray is entirely critical, and their order can play a key part in the ensuing investigation for target recognition, acknowledgment and picture pressure. Due to the nature of the SAR instrument, SAR pictures contain spot clamor, confusing the characterization of SAR pictures.

In this paper, we propose another multi-scale calculation for SAR order by joining MAR model, EM calculation for Gaussian blend model (GMM) with hereditary calculation.

Our methodology installs the EM calculation and the deterministic strengthening approach in the structure of the GA so that the properties of three calculations are used.

The populace based stochastic hunt of the GA investigates the hunt space more altogether than the EM technique.

In this way, our calculation empowers getting away from neighborhood ideal arrangements since the calculation turns out to be less touchy to its introduction. Our calculation likewise empowers the determination of the quantity of order in SAR picture utilizing the BIC standard.

3. Research Framework

Block segmentation:

The given input image of $N1*N2$ is further divided into non-overlapping blocks with a dimension of $S*S$.

Region labeling:

Once the identification of monotone, texture and edge block, and the pieces contiguous each other and have the same intensity and texture are associated and a basic locale name is given. For every piece, eight neighborhood availability is checked for its contiguousness with neighboring squares. For interfacing monotone squares, mean furthermore, difference shape the element vector and textural pieces, textural highlight vector containing its db4 wavelet parts is utilized for contrasting the neighboring surface pieces. Just comparative square sorts are looked at for nearness and combined to shape the same area. Let the element vector be spoken to as F_{ij} where i,j are block indices.

The two neighboring pieces (i,j) and $(i+1,j)$ have a place with the same area if the accompanying condition is fulfilled.

$$|F_{ij} - F_{i+1,j}|^2 < T$$

For each district accordingly associated, mark or locale number is given so that every district before the end of this procedure speaks to the particular monotone and texture areas. Edge squares are most certainly not considered in this procedure.

SVM Classification:

All picture pieces present in the whole picture are recognized either as monotone, texture or edge pieces and squares with comparative attributes contiguous each other are consolidated and areas are named.

SVM characterization is connected on the fragmented picture to recognize water, urban, vegetation and other unclassified zones.

4. Implementation

I have taken this as the image for classification and you can use any.



Fig 4.1 Image taken

First we have to import the libraries into Rstudio, as they must require for the processing (i.e raster package), Raster package will include 'brick', which will be used for plotting the image.

(*Code will be started with '#' symbol)

We have to plot the taken image for classification by setting the working directory to the folder in which the images are there using `setwd` command.

Here I am taking two images for creating training set (which will be used to classify the data) and testing set (which can be used to verify the classification whether it is done correctly or not). One with the water and other with the no water. These images also can be loaded into data frames for getting data by using the raster package only. By using the raster package we just loaded the images for usage, which will be used to make data frames. And this is how the training data looks like:



Fig 4.2 Pipelines



Fig 4.3 Background

In next step, we just transform these pixels into the perfect data frames using the following syntax and using 'names ()' will assign the RGB variable the names "r", "g", "b".

We will delete the background white pixels in next step, which are not required.

After deleting white background not require pixels, will create a variable indicating water pixels ('waterline').

After all this will combine the two data frames but will get almost the pixels in wide number so that will take only some of the pixels from all and can perform the model on less number of pixels only.

In next step, we will turn the variable in cofactor, which is required for the classification.

After this, for using any of the SVM model we should know how it is going to work for that I am dividing the total training data we get in last steps into train subset and test subset (with a condition that the data we take into the training subset should not be there in the test subset)

To use any of the SVM model we should use the 'e1071' package (it is said to feature the fastest SVM implementation for 'R') so that first we will add that package for future use

We use the default settings and perform a grid-search for the gamma and cost parameters in order to pick the best model by minimizing classification error via 10-fold-cross-validation.

As we discussed before, we are purely doing classification based on pixel color so that will give RGB values for prediction.

Even if you get a error resulting matrix, it is ok .It will indicate that the Model is rather than conservative in coding waterline.

The process is that first, we fit the SVM model with the whole training data set and then we use the predicted model and use the predicted pixels in the original map.

In order to visualize the result, we will create a copy of the raster object containing original map, and assign zeros and ones (instead of original RGB bands) to the pixels on the basis of the waterline/background predictions obtained by the SVM.

Finally, we can plot the classified image using image function (from the graphics package), and can slightly change the color settings in order to optimize the visibility of the waterline pixels. I use the image

instead of the plot function from the Raster package for esthetical reasons.

The Result image may look like:

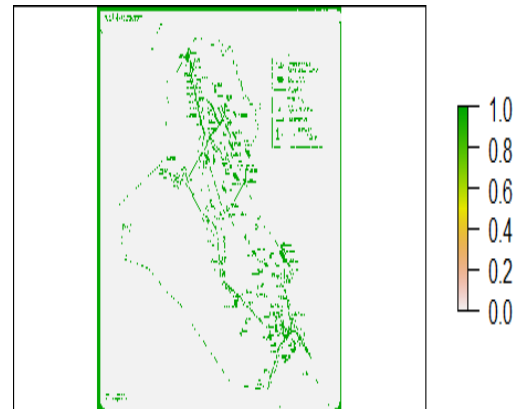


Fig 4.4 Output

5. Result

The issue we're managing here is basically on the premise of a raster picture (which a filtered delineate is), order every pixel into at least two classes. This is an issue in remote detecting, where normally multispectral satellite image is handled and pixels are allocated to land-cover classes (distinctive sorts of vegetation, developed ranges, and so forth.). Fortunately, for our application here, we are confronting a straightforward variation of this: our base material (the examined guide) is as of now profoundly straight-forward and the data we use for arrangement is just 3 dimensional (the three color groups making up the RGB picture).

For our issue, we are plainly going for supervised learning, since the classes into which we want to divide are very much characterized from the beginning and making training information to fit the model is very less. Classification of Synthetic Aperture Radar image can be achieved through this process and the results obtained are accurate enough

6. Future Work

1) I have used the SVM model with default settings but you can try other models of classifications like 'c-classification' that you may get the resultant original map with more accuracy.

2) You can also try the software like ArcMap (Which is the part of ArcGIS:which can be downloaded from <http://www.esri.com/>),which makes you work with it without coding.

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